

# The Design of Arduino Uno Based Automatic Concrete Maker

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## ABSTRACT

### Keywords

Arduino  
Concrete  
Loadcell  
Motor shield  
Otomatic

Making concrete manually is very time-consuming and energy-intensive. And if ordering concrete to the company can increase construction costs. The purpose of this research is to make concrete automatically with materials that are in accordance with Indonesian concrete standards so there is no need to order it again to the company. The tools used in this design are arduino uno , motor shield, sensors loadcell, servo motor, dc motor, solenoid valve, power supply, and button. The start button is connected to the pin on the arduino, then arduino is connected to the motor shield after it is connected to the servo motor, dc motor, loadcell, and the solenoid valve then given current by connecting the power supply to the motor shield and motor servo. The performance of this tool starts from pressing the button that matches the size of the concrete to be produced the the button signal will send to Arduino and the motor shield after that from the motor shield the signal is sent to the sand and rock servo motor, then it will be weighed with a loadcell sensor and poured what has been weighed into the blender to mix evenly, then the signal sent to the cement DC motor and solenoid valve to remove the cement and water to be mixed into the blender. After the stirring process is complete, the signal will be sent to the blender servo motor which will pour the concrete that has been processed. The design of the tool runs as desired.

## 1. Introduction

The development of technology today is growing rapidly from a manual system into a computer and software system. So that it can help the work that was originally done by humans become done with the help of the computer to be automated by programming the computer and software. Currently in the construction of small houses to supply concrete, always order concrete or make it yourself with a non-standard size, Jobs that are done manually can be far more effective but the work automatically is very helpful and saves time and simplifies human work. And the problems that occur when mixing concrete manually can waste time and energy and the size of concrete classified as outside the standard size of Indonesian concrete[1], by making automatic concrete tools, it can do compounding concrete in accordance with the recipe that has been standardized right. This tool is equipped with a servo motor and a dc motor to remove concrete material and a dc motor to run the blades and cement blades[2]. This tool is designed by using Arduino to move all components that exist.

## 2. The Proposed Method/Algorithm

### 2.1. Arduino

Arduino is an electric board that uses certain types of microcontroller. Ardino is a hardware output drom Arduino Italy, one of which is Arduino Uno, which is one of Arduino which is very common or very widely used to design automatic devices that need to microcontroller.[3]

### 2.2. Microcontroller Atmega328

Atmega 328 is a microcontroller output from atmel that has a RISC (Reduce Intruction Set Computer) architecture when every data execution process is faster than the other architecture, namely CISC (Completed Intruction Set Computer).[4]

### 2.3. Loadcell Sensor

Load cell are a core component of digital scales. In general, Load cell is used to calculate the mass of an object. A load cell sensor is composed of several conductors, a strain gauge, and a wheatstone bridge.[5]

### 2.4. Motor Shield

Motor Shield is an Arduino Shield that is easy to use for the use of wheeled robot applications or many use motor type tools, such as DC motors and servo motors. The Motor Shield itself is capable of moving 4 DC motors and 2 servo motors at once.[4][6]

## 3. Method

### 3.1. Hardware Design

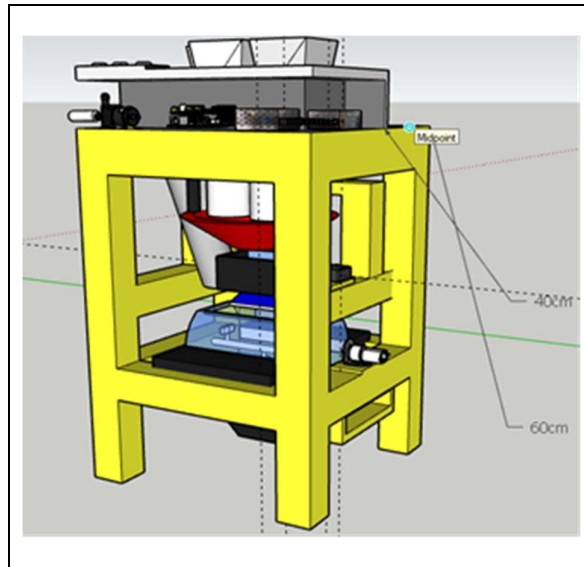


Fig. 1. Hardware Design

Hardware design is very important in the construction of tools, because at this stage there is an electrical circuit in order to reduce errors on the device. Hardware design show figure 1

### 3.2. Electrival Device Design

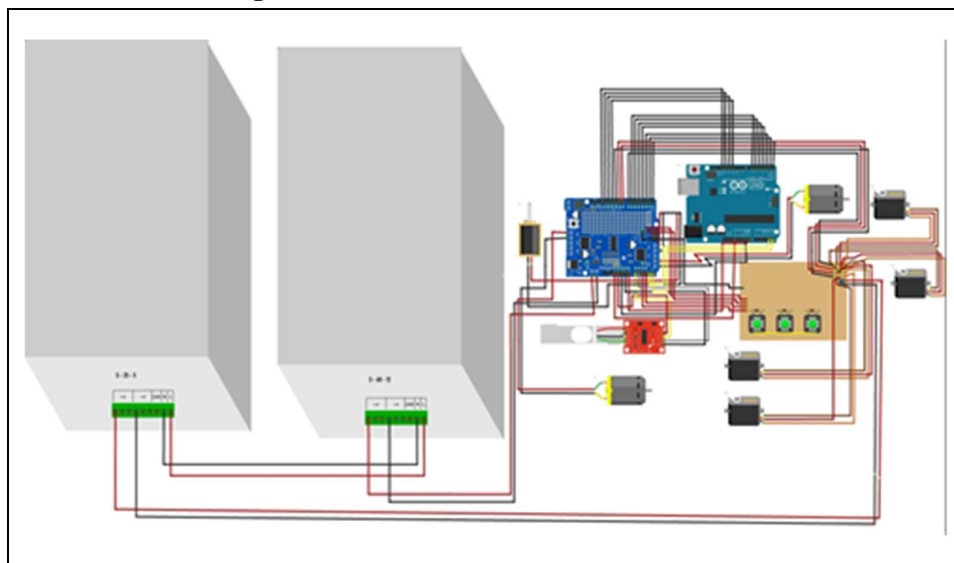


Fig. 2. Electrical Device Design

Table 1. Electrical Device design

Name I/O	Type	Pin Allocation
Button	Input	A1, A0, GND
Motor DC	Output	5V, GND
Motor Servo	Output	5V, GND, D9, D10, D8, D7
Load Cell	Output	5V, A0, A1, GND, VCC, DAT, CLK, GND
Solenoid Valve	Output	5V, GND
Power Supply	Output	V+, V-

3.3. Flowchart System

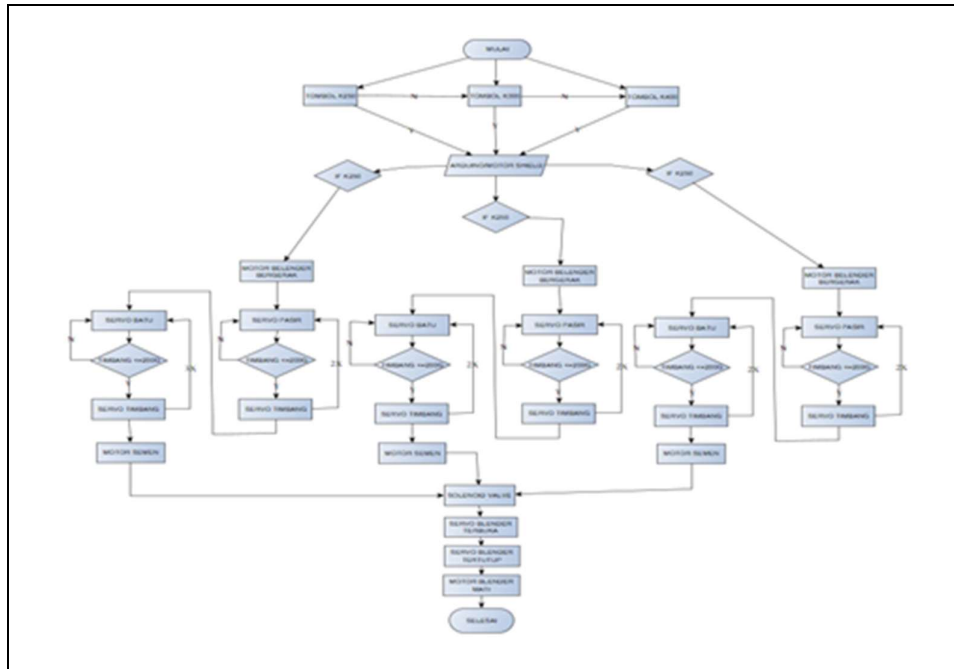



Fig. 3. Flowchart System

From the flowchart figure 3, it can be seen the working process of the tool being built. It starts by pressing one of the three buttons provided then the signal is sent to Arduino and the Shield motor, after which the signal will be sent to the DC belender motor and then proceed to the sand servo motor, if sand  200 grams the weighing process will continue

## 4. Results and Discussion

### 4.1. Tool Designing Result



Fig. 4. Software Design

The figure 4 is the result of designing an automatic concrete maker that has been installed with all its components such as Arduino, motor shield, DC motor, servo motor, solenoid valve, loadcell and power supply.

### 4.2. Software Design Result

The result of software design on this tool system using Arduino IDE software. In this program contains commands to move the motor, buttons, and scale calibration. Show figure 5

```
WOKe | Arduino 1.8.12
File Edit Sketch Tools Help
WOKe
#include <Servo.h> // librari untuk motor servo
#include <AFMotor.h> // librari untuk motor
#include "HX711.h" //librari untuk load cell (timbangan)

#define DOUT A0
#define CLK A1
HX711 scale(DOUT, CLK);
float calibration_factor = 350.00; //kalibrasi timbangan (faktor pengali)
int GRAM;

//const int air = 6;
const int K250 = 2;
const int K300 = 3;
const int K400 = A2;
//const int ledPin = 13;
const int speed = 100; // percent of maximum speed

#include <AFMotor.h> // adafruit motor shield library (modified by sm)
AF_DCMotor Motor_Left_Front(4, MOTOR34_1KHZ); // Motor 4
AF_DCMotor Motor_Right_Front(3, MOTOR34_1KHZ); // Motor 3
AF_DCMotor Motor_Left_Rear(2, MOTOR12_1KHZ); // Motor 1
AF_DCMotor Motor_Right_Rear(1, MOTOR12_1KHZ); // Motor 2

int pin;

int tombol_K250 = 0;
int tombol_K300 = 0;
int tombol_K400 = 0;
```

Fig. 5. Software Design

Furthermore, the picture below is a program for loadcell sensor calibration, because without calibration the scales will not fit, especially with the hanging position of the scales which requires periodic calibration, in order to get a fixed value. In carrying out the calibration, as well as first having to introduce with Arduino then enter the calibration value that is set to the pin that has been determined in the motor shield. Show figure 6



```

KALIBRASI_TIMBANGAN_LOAD_CELL | Arduino 1.8.12
File Edit Sketch Tools Help
KALIBRASI_TIMBANGAN_LOAD_CELL
#include "HX711.h"
#define DOUT A0
#define CLK A1
HX711 scale(DOUT, CLK);
float calibration_factor = 450;
int GRAM;

void setup() {
  Serial.begin(9600);
  Serial.println("Tekan a,s,d,f untuk menaikan calibration_factor ke 10,100,1000,10000");
  Serial.println("Tekan z,x,c,v untuk menurunkan calibration_factor ke 10,100,1000,10000");
  scale.set_scale();
  scale.tare();
  long zero_factor = scale.read_average();
  Serial.println("Zero factor: ");
  Serial.println(zero_factor);
  delay(1000);
}

void loop() {
  scale.set_scale(calibration_factor);
  GRAM = scale.get_units(1);
  Serial.println("Reading: ");
  Serial.println(GRAM);
  Serial.println(" Gram");
  Serial.println(" calibration_factor: ");
  Serial.println(calibration_factor);
  Serial.println();
}
    
```

Fig. 6. Loadcell Sensor Calibration Program

### 4.3. Testing Result

After designing the automatic concrete making equipment, it is necessary to test the tool. Testing this tool aims to ensure this tool works properly, as expected. Especially in terms of the size of the material used, because this tool has 3 sizes.

#### 4.3.1. The Accuracy of the K250 Concrete

This test is carried out to ensure the accuracy of the material from K250 concrete, because sand and stone are measured with a scale using a Loadcell sensor, this test is taken to ensure the tolerance size of each K250 concrete production.

Table 2. K250 Concrete Testing Result

<i>Activities</i>	<i>Sand Size (g)</i>	<i>Stone Size (g)</i>
Necessary Materials	100	200
First Production Test	106	194
Second Production Test	98	210
Third Production Test	101	210
Fourth Production Test	100	201
Fifth Production Test	110	200
Sixth Production Test	100	201
Seventh Production Test	98	206
Eight Production Test	105	200
Ninth Production Test	100	205
Tenth Production Test	101	198

From the test Table 2 the concrete material has a small size tolerance, meaning that the calibration of the scales and servo motor works well, as expected. So the tolerance obtained is 10g. then the K250 concrete test results are considered successful.

#### 4.3.2. Materials of K300 Concrete Accuracy Test Results

This test is carried out to ensure the accuracy of the material from K300 concrete, because sand and stone are measured with a scale using a Loadcell sensor, this test is taken to ensure the tolerance size of each K300 concrete production.

Table 3. K300 Concrete Testing Result

<i>Activities</i>	<i>Sand Size (g)</i>	<i>Stone Size (g)</i>
Necessary Materials	120	200

First Production Test	123	206
Second Production Test	125	201
Third Production Test	115	200
Fourth Production Test	120	205
Fifth Production Test	120	200
Sixth Production Test	128	201
Seventh Production Test	110	190
Eight Production Test	119	200
Ninth Production Test	121	200
Tenth Production Test	120	201

From the test Table 3 the concrete material has a small size tolerance, meaning that the calibration of the scales and servo motor works well, as expected. So the tolerance obtained is 10g. then the K300 concrete test results are considered successful.

#### 4.3.3. Materials of K400 Concrete Accuracy Test Results

This test is carried out to ensure the accuracy of the material from K400 concrete, because sand and stone are measured with a scale using a Loadcell sensor, this test is taken to ensure the tolerance size of each K400 concrete production. Show table 4

**Table 4.** K400 Concrete Testing Result

<i>Activities</i>	<i>Sand Size (g)</i>	<i>Stone Size (g)</i>
Necessary Materials	150	250 g
First Production Test	156	252 g
Second Production Test	148	256
Third Production Test	150	246
Fourth Production Test	155	250
Fifth Production Test	152	258
Sixth Production Test	150	246
Seventh Production Test	148	250
Eight Production Test	156	258
Ninth Production Test	150	250
Tenth Production Test	155	251

#### 4.3.4. Servo Motor Testing Results

This servo motor test is carried out so that it can monitor the performance of the four servo motors that are moving.

**Table 5.** Servo Motor Testing Result

<i>Activities</i>	<i>Sand Servo</i>	<i>Stone Servo</i>	<i>Pour Servo</i>	<i>Blender Servo</i>
Production 1	Succeed	Succeed	Succeed	Succeed
Production 2	Succeed	Succeed	Succeed	Succeed
Production 3	Succeed	Succeed	Succeed	Succeed
Production 4	Succeed	Succeed	Succeed	Succeed
Production 5	Succeed	Succeed	Succeed	Succeed
Production 6	Succeed	Succeed	Succeed	Succeed
Production 7	Succeed	Succeed	Succeed	Succeed
Production 8	Succeed	Succeed	Succeed	Succeed
Production 9	Succeed	Succeed	Succeed	Succeed
Production 10	Succeed	Succeed	Succeed	Succeed

From the Servo Motor testing table 5 it can be concluded that the performance of the four servo motors is very good according to the instructions made through the Arduino IDE program.

#### 4.3.5. Tool Success Rate

The success rate of the tool is very important to see how successful the tool is made.

**Table 6.** Percentage of tool success for each production

Concrete Types	Percentage of Success (%)
K250 Concrete Production	95
K300 Concrete Production	95
K400 Concrete Production	95

Numbers 95% of 100% obtained from the success rate of tools in producing K250, K300, and K400 concrete. The success itself is seen from the servo performance and the accuracy of the material that has been tested. From the accuracy of the material still requires a tolerance value of 10g, then the success rate of the tool becomes 95% because the accuracy of the material still requires still requires tolerance.

#### 5. Conclusion

1. Based on the test result, this automatic concrete maker succeed in producing concrete with K250, K300, K400 quality, even though it needs 10 g material.
2. By using this tool makes concrete making is much more effective and saves energy and costs.
3. from the results of the belender strength testing can be concluded. In the blender that is made is still not perfect, because there are still a lot of water leakage in the built blender.

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